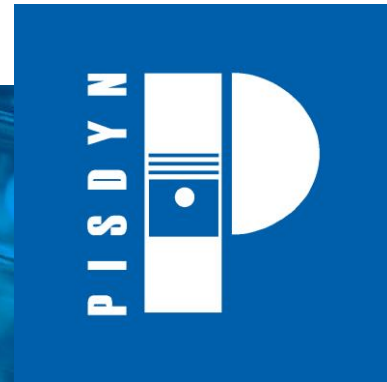
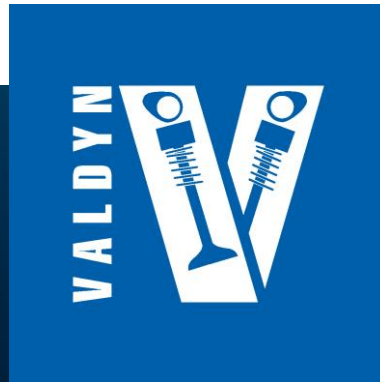
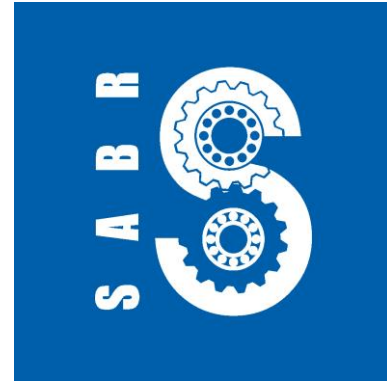


Mechanical Suite 2017.1 New Features



Our Mechanical Suite of products include ENGDYN, VALDYN, PISDYN and RINGPAK



General Kinematic and Dynamic System Analysis

Driveline and Transmission Analysis

Cam Design and Valvetrain Analysis

Ring Pack Design

Cranktrain Analysis

Powertrain NVH

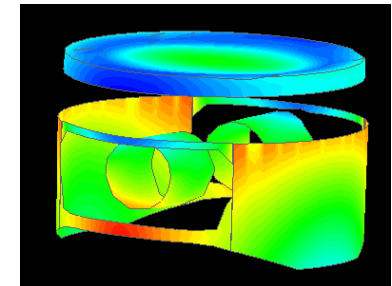
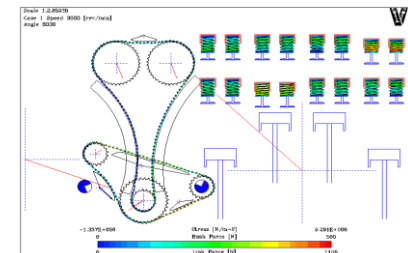
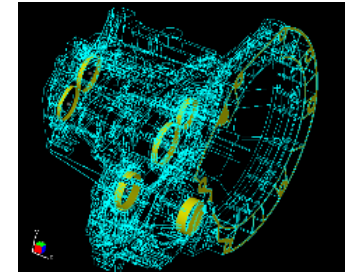
Powertrain Durability

Bearing Analysis

Gear, Chain, and Belt Dynamics

Engine System Dynamics

Piston Design

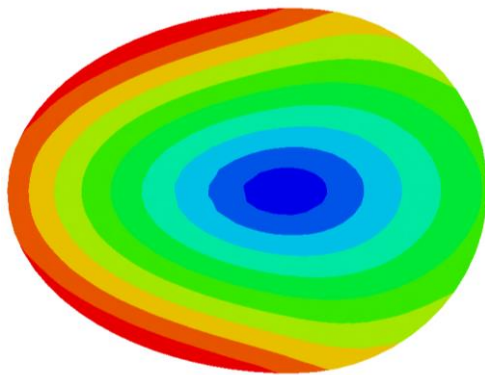


Ovate Spring

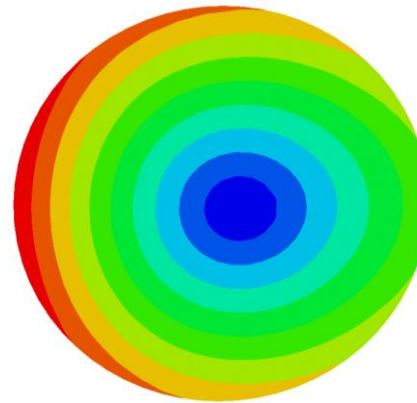
capability



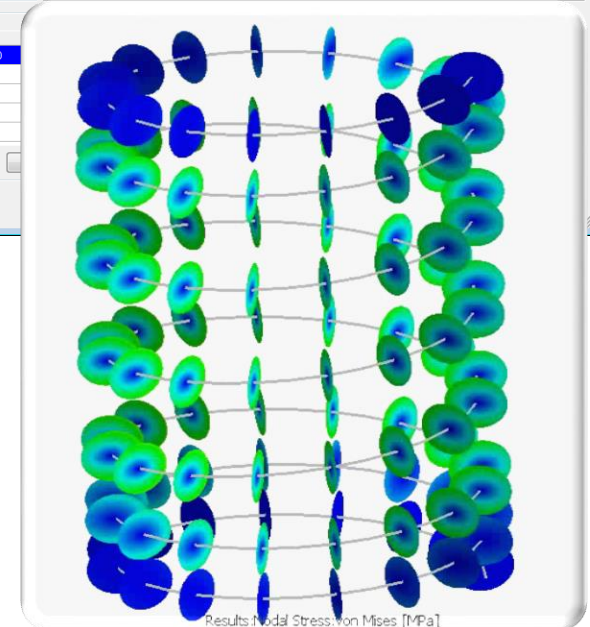
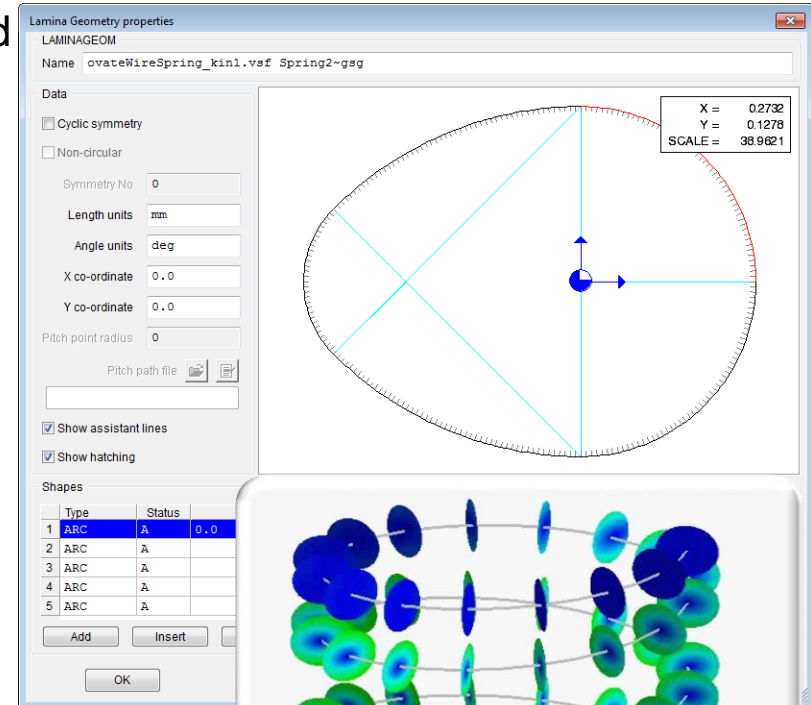
- Ovate (arbitrary section) springs in VALDYN and VALDYN Kinematics
 - 1D kinematics
 - Legacy and VALDYN-Kinematic GUI's
 - 1D and 3D dynamics
 - Embedded FE calculation using FEARCE
 - Uses St. Venant's theorem to evaluate torsional constant and stresses
 - Supports any convex spring section



Ovate Section



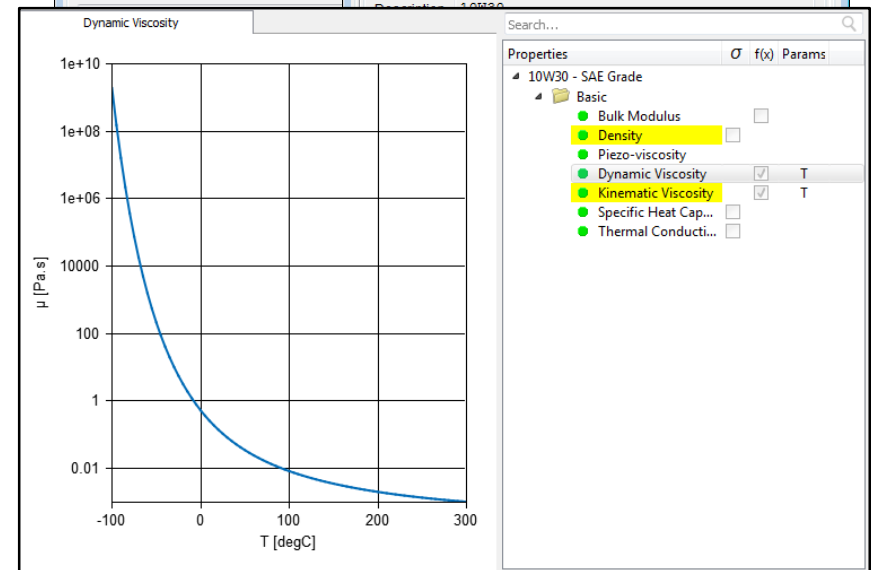
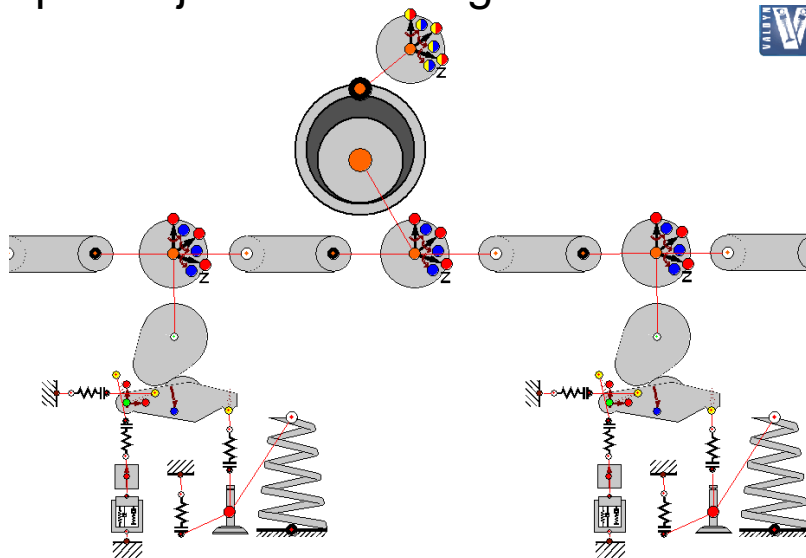
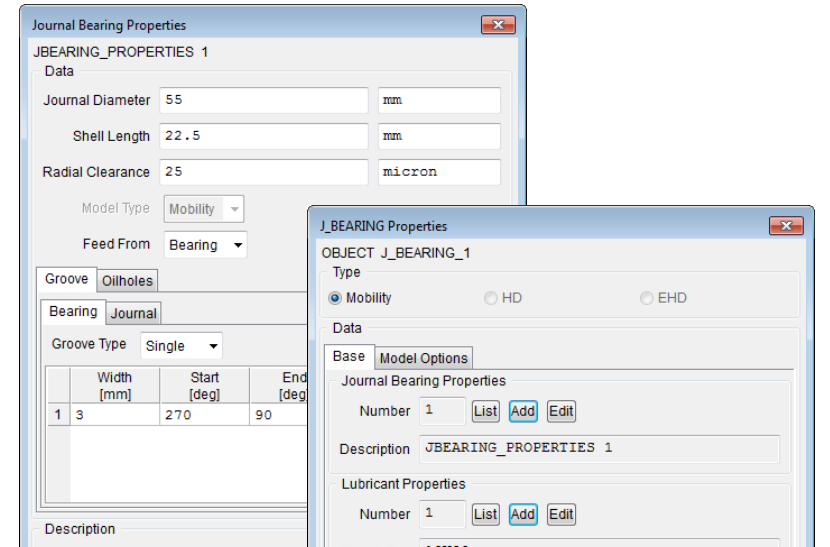
Elliptical Section



capability



- New JBEARING Journal Bearing object
 - Mobility based model from ENGDYN
 - Thermal balance option
 - EHL model to follow in 2018
 - Selection of Lubricant properties using Material Editor
 - Typical applications include modelling camshaft, balancer shaft and gear pinion journal bearings

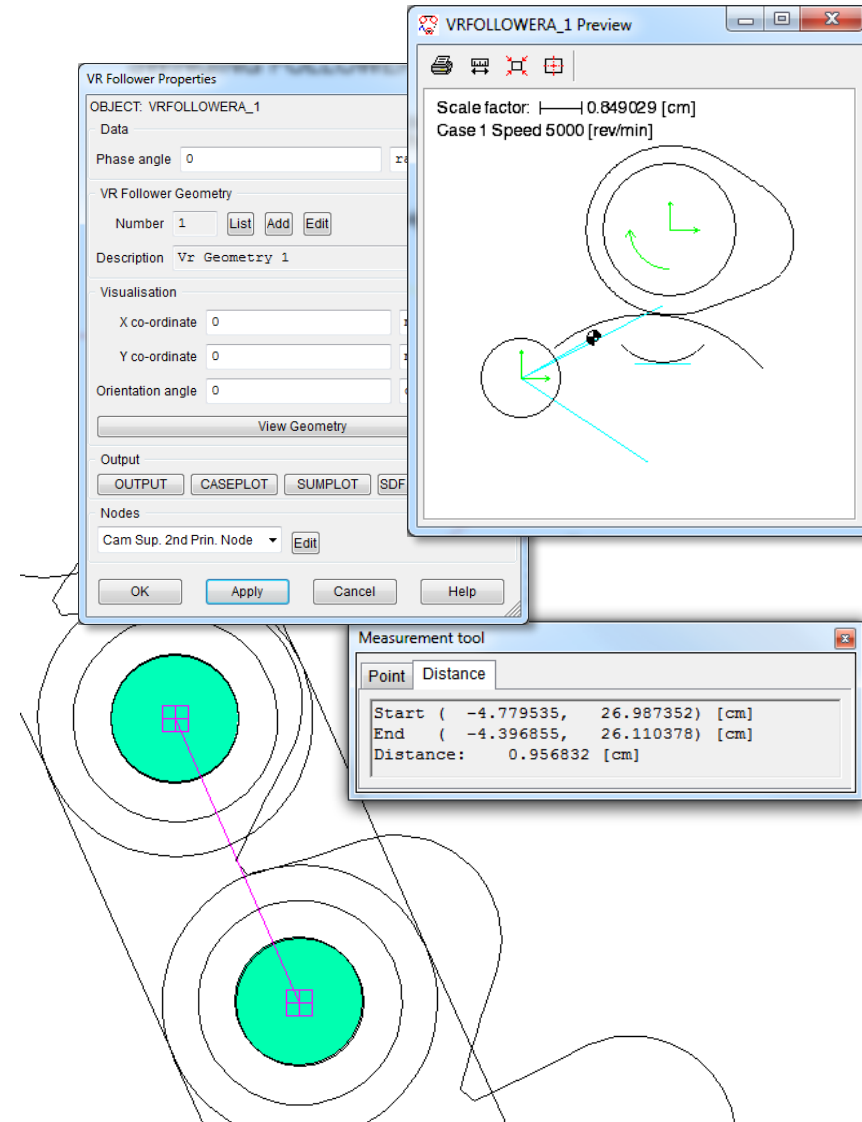


Visualization improvements

usability



- 2D visualization of objects
 - A tool that enables a rapid verification of the intended geometry
 - VRGEOM currently supported, others to follow
- Animator measurement tool
 - Measuring distances directly in the animator

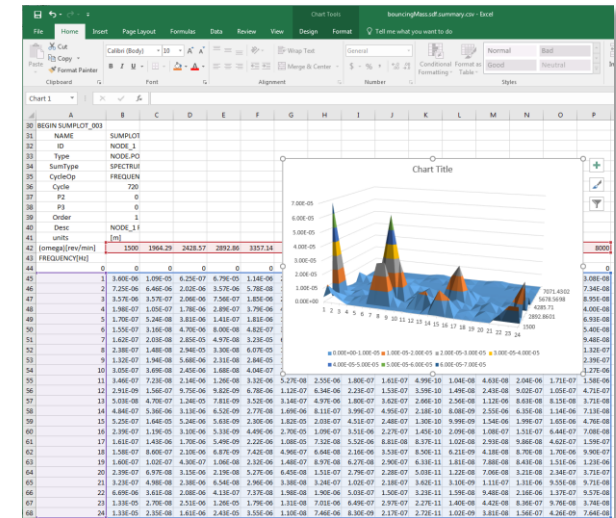
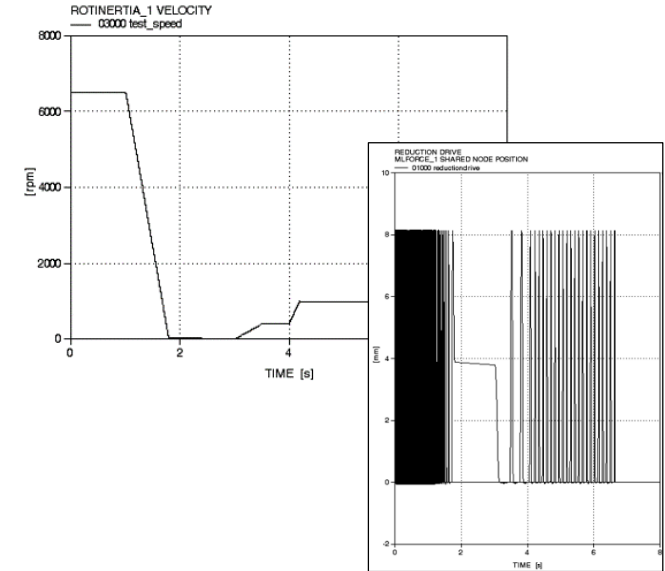


Mechanical Suite 2017.1

flexibility and capability



- Velocity profiles now supports contiguous zero-velocity sections
 - Enables to run a start-stop simulation or co-simulate such a simulation with WAVE
- Asperity contact area as an output from OILFILM Object
- SUMPLOT data stored directly in SDF
 - A CSV file is always exported from the SDF results file, and includes all the SUMPLOTS defined in the VALDYN model.

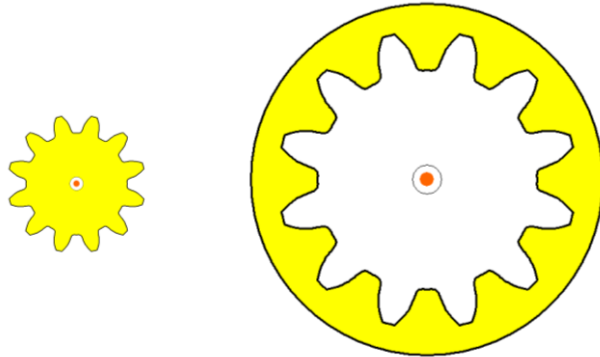


Improved GEAR3D Object

capability and usability



- Explicit Mesh Type input
 - External and Internal (Ring) types
 - Icon changes based on type



Gear3D Properties

OBJECT GEAR3D_1

Type

☐ Non-FE model ☒ FE model

Mesh type

☒ External gear ☐ Internal (ring) gear

Data

Base **Stiffness & Profile** Generate compliance matrix

Number of teeth 40

Gear module 4 mm

Addendum modification 0

Normal pressure angle 20 deg

Helix angle 25 deg

TIF/root diameter 170.001 mm

Tip diameter 183.7 mm

Tooth face width 18 mm

Slices over face width 10

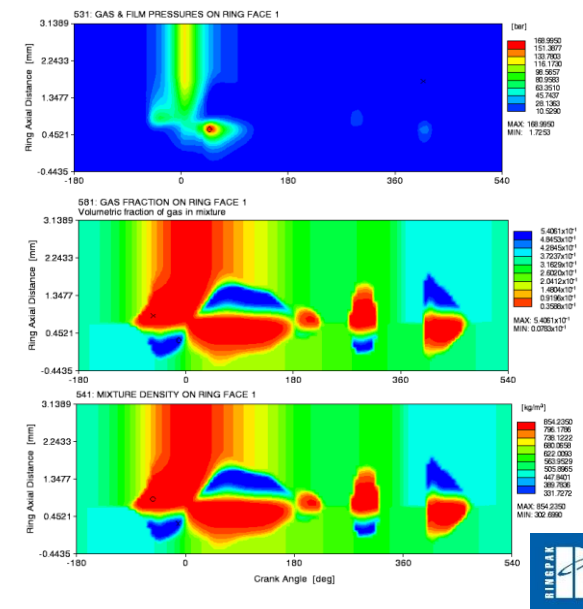
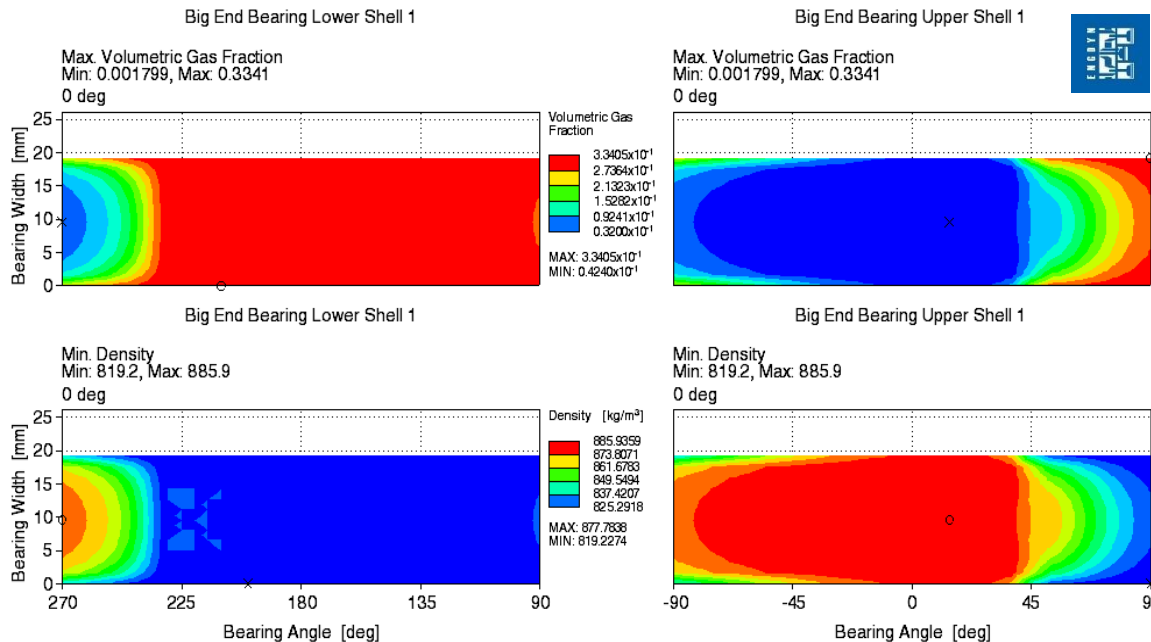
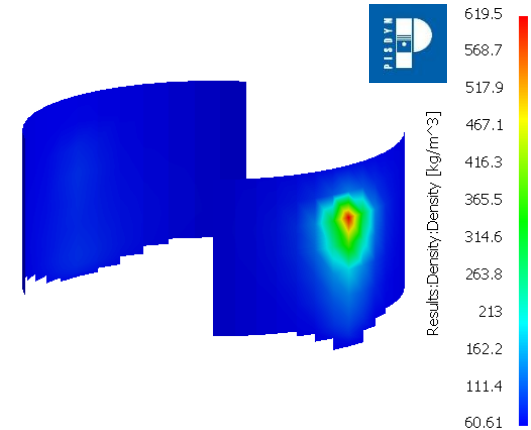
Output

Aerated oil for lubricated surfaces

capability



- Support of aerated oil with solution of the compressible form of the Reynolds equation for all lubricated interfaces for ENGDDYN, PISDYN and RINGPAK
 - Aeration of oil can have significant effects to behaviour of the lubricated surfaces. These effect can be negative by reducing of the oil film bearing capacity, but can be also quite positive by reducing of shear stress and overall friction.

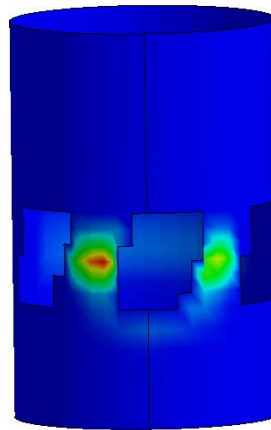
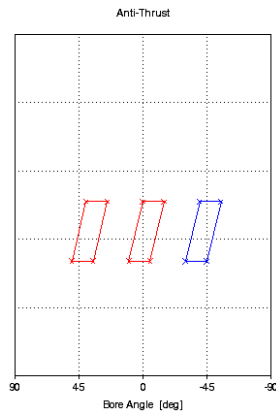


Enhanced functionality and solver improvements

capability and speed



- Support of ports on cylinder bore with the New PISDYN Solver
 - Enhanced functionality and model set-up
 - Support of non-symmetrical ports



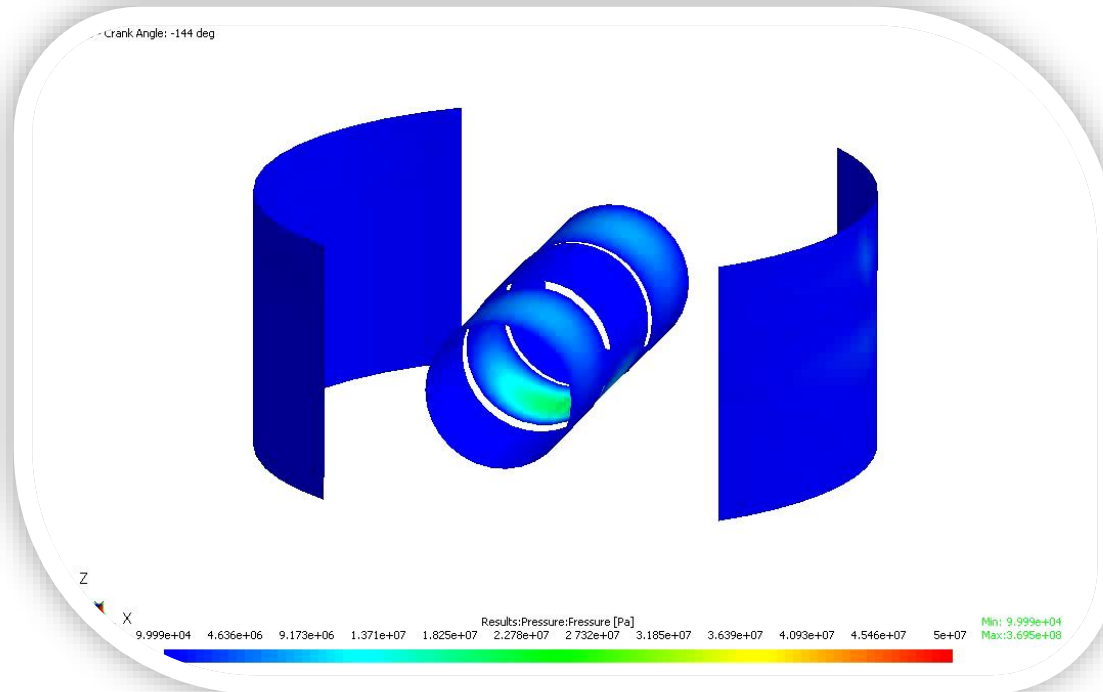
- Improved robustness of the New PISDYN Solver

Piston secondary motion animation in R-Desk

usability



- Enables animating of piston primary motion and/or secondary motion and combining it with displacements and deformations

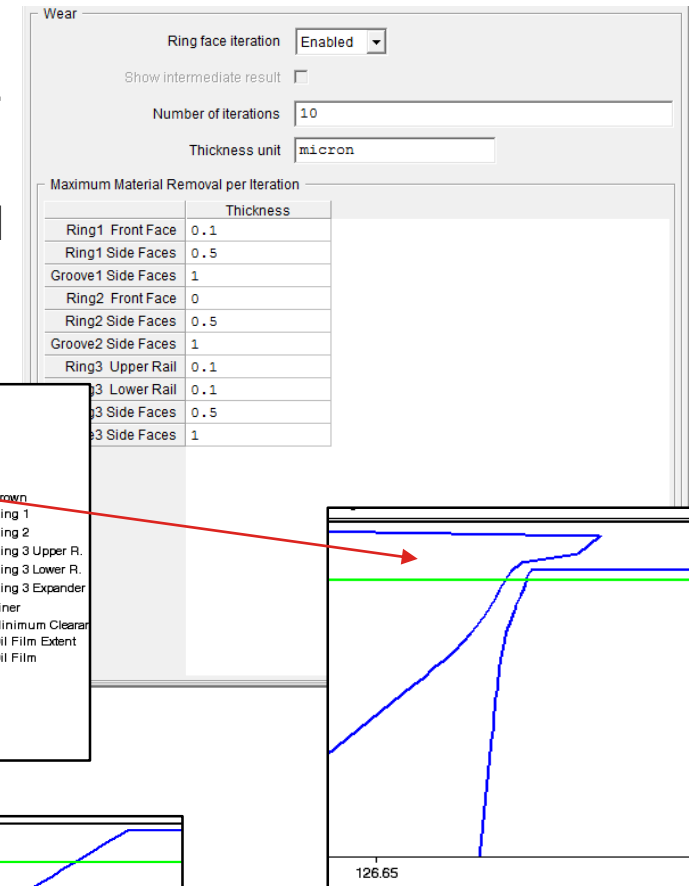


Extension of wear iteration model

capability



- Now the extension of wear iteration model to includes Ring-Groove interfaces as well as Ring-Liner interface
 - Outputs showing evolution of material removal are written to separate .rp file



Dynamic connecting rod model now available for dynamic solution

capability



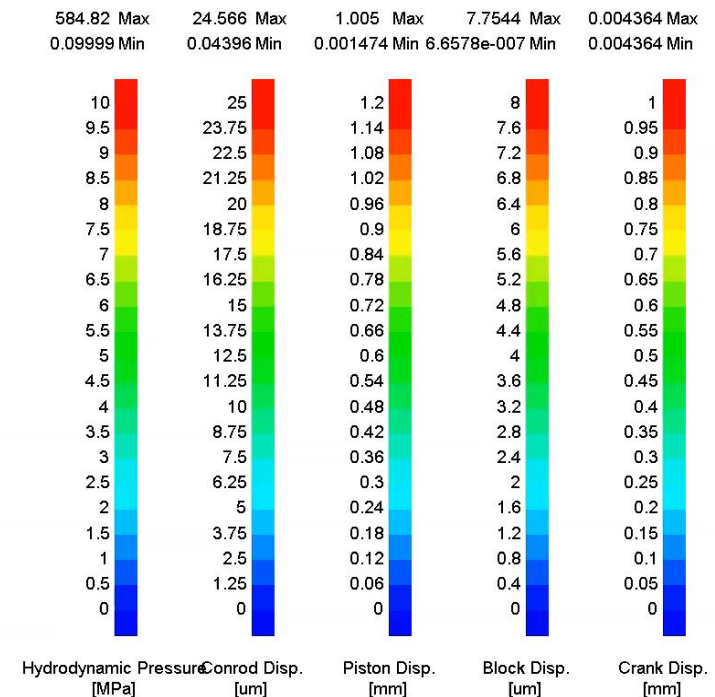
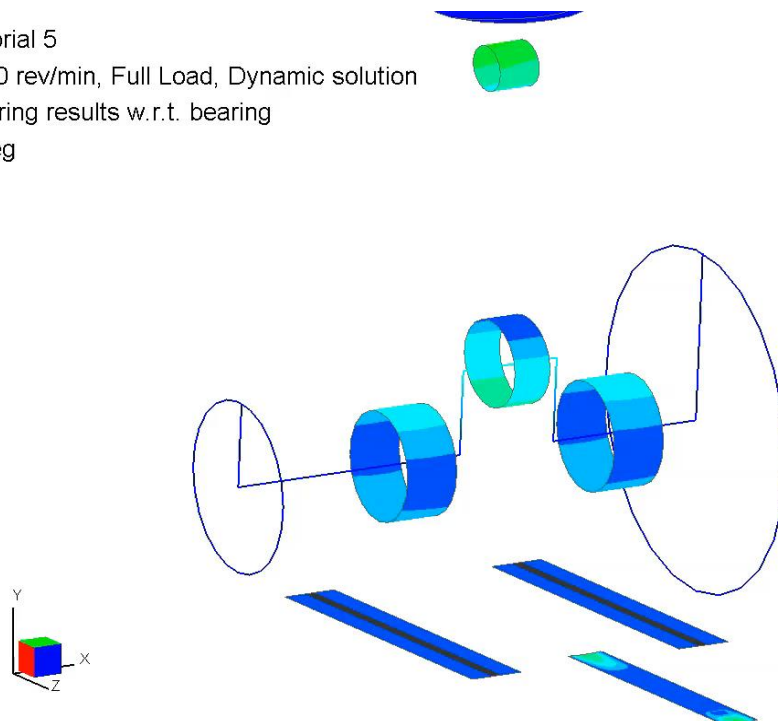
- Mobility based and EHL solutions at big end and small end bearings
- CMS Dynamic Body model of connecting rod
- Coupled solution between big end bearing and crank pin journal

Tutorial 5

4000 rev/min, Full Load, Dynamic solution

Bearing results w.r.t. bearing

1 deg



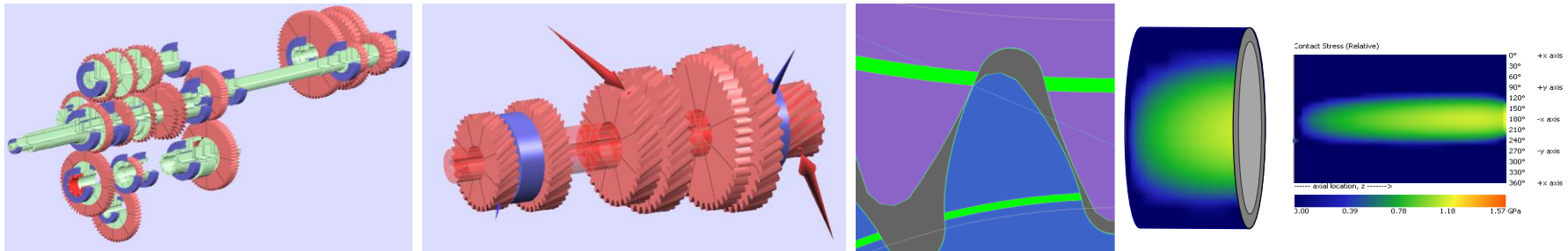
What is SABR?

SABR is a quasi-static transmission structural program for the design and analysis of shaft, bearing, and geared systems

- Rapid modelling, solver speed, and stability combined with geometric warnings and guidelines makes SABR users highly productive for minimal cost



- Easy to use
- Multi-core processing for solving completed in seconds



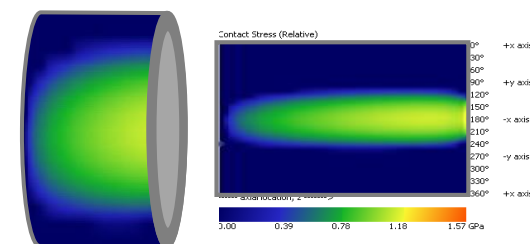
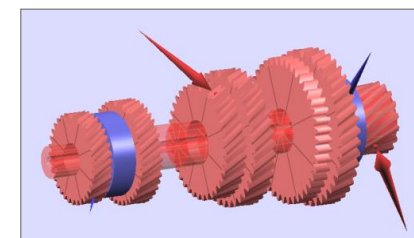
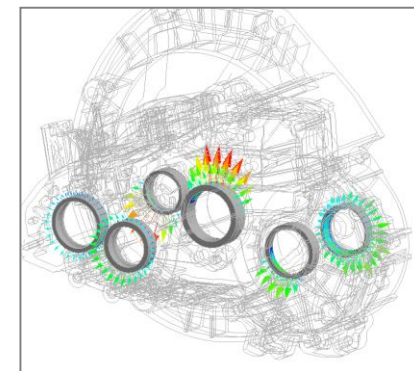
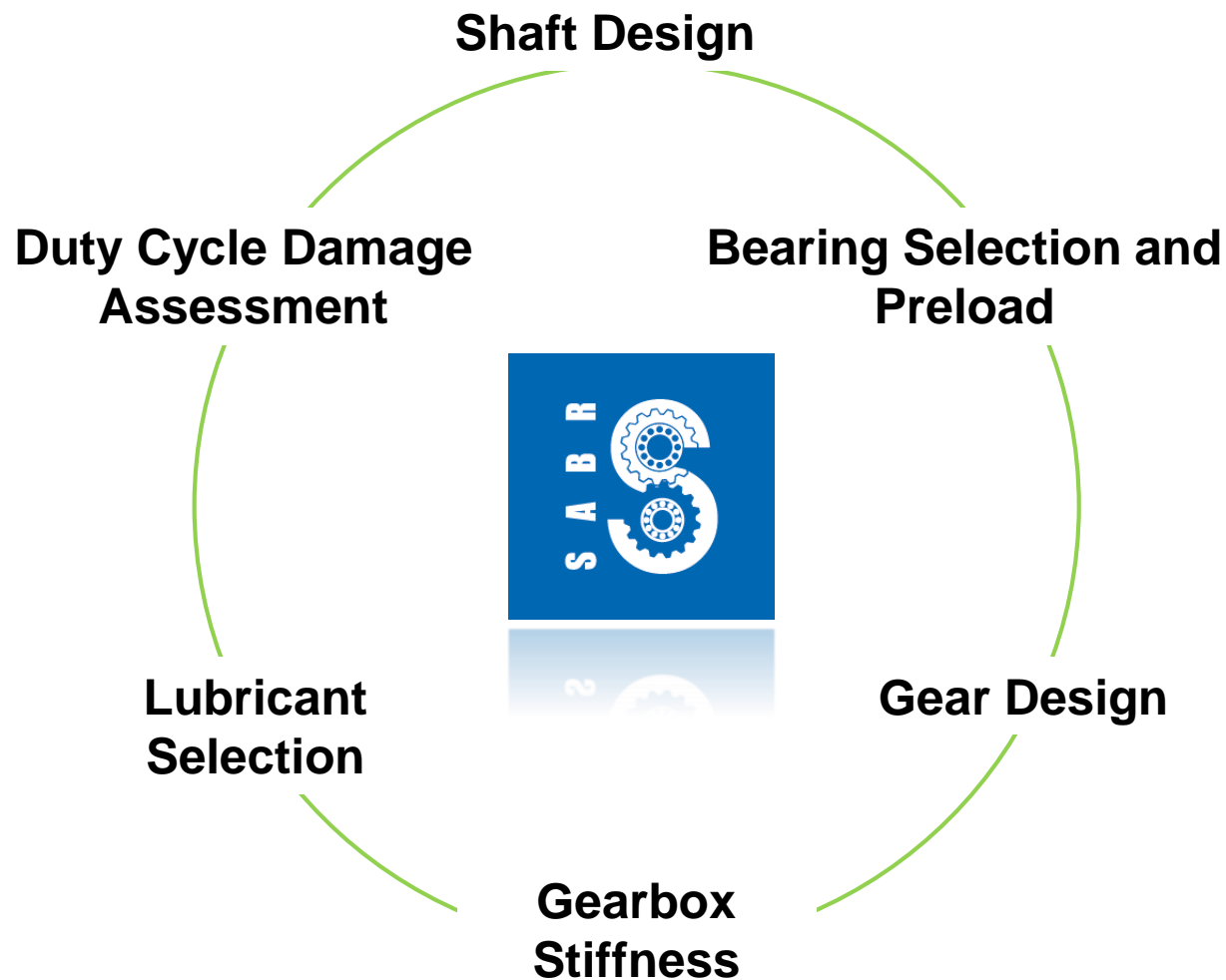
Intuitive

Fast

Immediate Feedback

Productive

SABR provides analysis capabilities for the design and optimisation of shafts, bearings and gears



New Features

capability



- Import Duty Cycle now supports multiple Input/Output shafts

Duty Cycle File Load Preview (Table format)

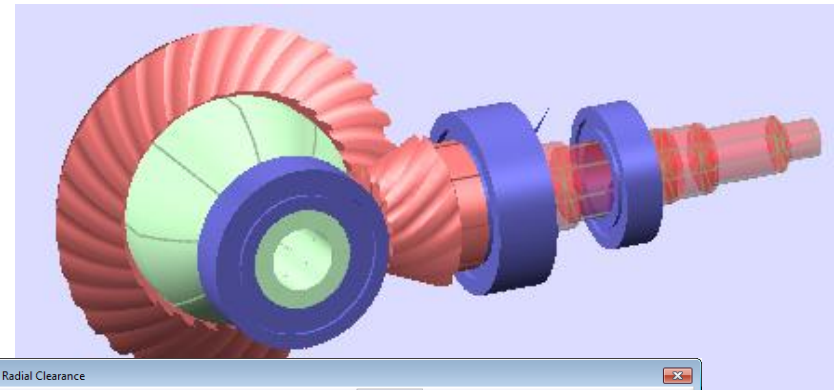
Raw Data Options Final Data

These are the load cases read from the file. Please check them carefully.
If the data is not what you expect, please check the Options tab

Number of Load Cases 8

Powerflow	Load Case	Time (hrs)	Temperature (°C)	Speed (rpm) Main Shaft ICE Input	Speed (rpm) EMA Shaft	Speed (rpm) EMB Shaft	Torque (Nm) Main Shaft ICE Input	Torque (Nm) EMB Shaft	Torque (Nm) EMA Shaft
(hEV) Hybrid mode	High 1	48.000	70.000	3995.000	6600.000		305.000	60.000	
(hEV) Hybrid mode	High 2	8.000	70.000	3042.000	7700.000		286.600	280.000	
(hEV) Hybrid mode	Max Torque hEV	0.001	70.000	3995.000	6600.000		311.000	305.000	
(EV) Electric mode	(EV) Electric mode Fwd	34.000	70.000			1100.000		200.000	-90.000
(EV) Electric mode	Regen	14.000	70.000			2000.000		-310.000	0.000
(EV) Electric mode	Reverse	16.000	70.000			-2000.000		-290.000	0.000
(EV) Electric mode	Max Torque EV Fwd	0.001	70.000			-6750.000		315.000	-74.000
(EV) Electric mode	Max Torque EV Rev	0.001	70.000			-1013.000		-315.000	74.000

- Hypoid Gears – Forces and misalignment calculation
 - All 4 ISO methods of calculation implemented
 - Geometry and Loads to ISO 23509
 - Misalignments to SAE 750152



- Faster loading of custom lubricants

Operating Radial Clearance

Clearance Before Mounting 13.000 µm

Mounting Details

"Shaft"		"Housing"	
Nominal Shaft OD	40.000 mm	Nominal Housing Bore	52.000 mm
Bearing Bore Deviation	-12.000 µm	Bearing OD Deviation	-13.000 µm
ISO 286 Fit Class	H5	ISO 286 Fit Class	H7
Clearance (+) / Interference (-)		Clearance (+) / Interference (-)	
Probable	-10.000 µm	Probable	14.000 µm
Min/Max	-18.000 5.000 µm	Min/Max	0.000 43.000 µm
Interference Multiplier	0.7	Interference Multiplier	0.8
Change in bearing clearance = fit interference x multiplier. If fit clearance >= 0, there is no effect on bearing clearance			
Clearance Change	-7.000 µm	Clearance Change	0.000 µm
Min/Max	-12.600 0.000 µm	Min/Max	0.000 0.000 µm
Clearance After Mounting		6.000 µm	
Min/Max		0.400 13.000 µm	